Lecture Notes in Electrical Engineering 1046

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Proceedings of the 4th International Conference on Communication, Devices and Computing

ICCDC 2023

Springer

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ISSN 1876-1100 ISSN 1876-1119 (electronic)
Lecture Notes in Electrical Engineering
ISBN 978-981-99-2709-8 ISBN 978-981-99-2710-4 (eBook)
https://doi.org/10.1007/978-981-99-2710-4

This Springer imprint is published by the registered company Springer Nature Singapore Pte Ltd.
The registered company address is: 152 Beach Road, #21-01/04 Gateway East, Singapore 189721, Singapore

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Performance Comparisons of MPEDE-Based Integer and Fractional-Order PID Controllers for a Cruise Control System

Mou Das Mahapatra, Shibendu Mahata, Ritu Rani De, Rajani Kanta Mudi, and Chanchal Dey

Abstract An effective technique for the optimal design of fractional-order proportional-integral-derivative (FOPID) controller in a cruise control application is presented. The minimization of step response error is formulated as an objective function. Such a proposal avoids evaluating the transient and steady-state response parameters at run-time of the optimizer. The optimization is carried out using a multi-population ensemble differential evolution (MPEDE) method. Comparisons with a classical PID controller also designed using MPEDE demonstrate the faster response time for the FOPID controlled system. The superiority of the proposed fractional controller over those of the recently reported models is demonstrated using various performance metrics.

Keywords Cruise control system · Fractional-order controller · Multi-population ensemble differential evolution · Optimization · PID controller

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D. K. Sarkar et al. (eds.), *Proceedings of the 4th International Conference on Communication, Devices and Computing*, Lecture Notes in Electrical Engineering 1046, https://doi.org/10.1007/978-981-99-2710-4_15