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xvi Contents

Prediction of Client Term Deposit Subscription Using Machine	0.2
Learning Muskan Singh, Namrata Dhanda, U. K. Farooqui, Kapil Kumar Gupta, and Rajat Verma	83
Real Estate Price Prediction Using Machine Learning	95
A Comparative Study to Detect Cervical Dysplasia by Using Pap Smear Images Jheelam Mondal and Subhankar Joardar	113
Design of a Cost-Effective Remote Health Monitoring System Using IoT Subhadeep Paul, Madhusudan Maiti, Dibyendu Chowdhury, and Subhas Chandra Saha	125
Current Exploration in Microfluidics-Based Point-Of-Care Biosensor Applications: A Review Pitam Chakrabarti, Sucheta Das, and Shamba Chatterjee	139
A Review on Memristor-Based Reactance-Less Relaxation Oscillator Rajesh Dutta, Amiya Karmakar, and Sudakshina Kundu	149
Optimal Control and Voltage Sag Compensation in a PV/FC Integrated Microgrid Through Biography Based Optimization Technique Gagan Kumar Sahoo, Subham Mohanty, and Subhashree Choudhury	159
Performance Comparisons of MPEDE-Based Integer and Fractional-Order PID Controllers for a Cruise Control System  Mou Das Mahapatra, Shibendu Mahata, Ritu Rani De, Rajani Kanta Mudi, and Chanchal Dey	177
Novel CMOS 1-Digit BCD-Adder Correction Circuit  Shatabhisa Goswami, Ananya Mandal, Aishikee Mishra, Joyoshri Goswami, and Aloke Saha	189
<b>Digital Image Tampering Detection Using Deep Learning: A Survey</b> Sunen Chakraborty, Paramita Dey, and Kingshuk Chatterjee	197
Nanorod Shaped TiO <sub>2</sub> Photoanode and Mixed Halide Absorber-Based Perovskite Solar Cell Device Fabrication Anitesh Anand, Niranjan Polai, Madhu Paswan, Manas Mishra, Chanchal Kumar De, and Debasis De	217

## Performance Comparisons of MPEDE-Based Integer and Fractional-Order PID Controllers for a Cruise Control System



Mou Das Mahapatra, Shibendu Mahata, Ritu Rani De, Rajani Kanta Mudi, and Chanchal Dey

**Abstract** An effective technique for the optimal design of fractional-order proportional-integral-derivative (FOPID) controller in a cruise control application is presented. The minimization of step response error is formulated as an objective function. Such a proposal avoids evaluating the transient and steady-state response parameters at run-time of the optimizer. The optimization is carried out using a multi-population ensemble differential evolution (MPEDE) method. Comparisons with a classical PID controller also designed using MPEDE demonstrate the faster response time for the FOPID controlled system. The superiority of the proposed fractional controller over those of the recently reported models is demonstrated using various performance metrics.

**Keywords** Cruise control system  $\cdot$  Fractional-order controller  $\cdot$  Multi-population ensemble differential evolution  $\cdot$  Optimization  $\cdot$  PID controller

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