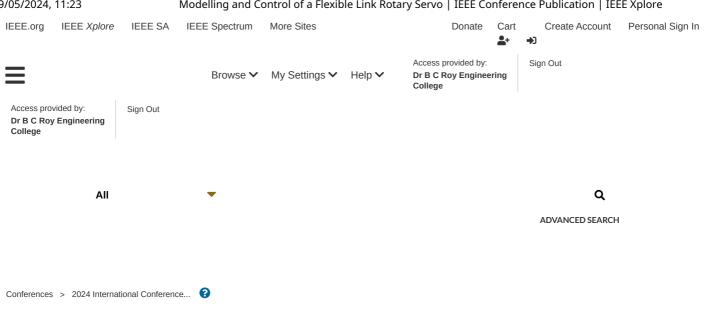
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<u>SL</u>	<u>Paper</u>	<u>Authors</u>	Paper Title		
<u>No</u>	<u>ID</u>				
1	26	Prashant Kumar, Sabha Raj Arya, Rahul Bosu	Impementation of Self-Learning ANN-ANFIS based Dynamic Voltage Restorer for Voltage Power Quality Improvement		
2	44	Liya M L, Aswathy M	Impact of basic communication modules and techniques in humanitarian crisis-a brief survey		
3	47	Chaity Sarkar, Srijan Banerjee, Gyan Prakash, Kingsuk Majumdar, Ranjan kumar Jha	Modelling and control of a flexible link rotary servo		
4	70	Debraj Roy, Trilok Nath Pandey, Bibhuti Bhusan Dash, Sudhansu Shekhar Patra, Utpal Chandra De, Abinash Tripathy	Intelligent Analysis and Identification of Palm Gestures using ML Algorithms		
5	95	Chandan Jana, Debolina Pradhan, Sannistha Banerjee, Mousumi Jana Bala	Optimal Placement of Distributed Generation for Minimization of Power Loss, Carbon Emission and Voltage Deviation Considering Demand Uncertainty		
6	97	Manikandan C, Ankit Kashyap, Fakira Mohan Nahak	AI's Influence on Cinematic Restoration		
7	110	Ayse Ozates, Erhan Akin, Aykut Bilgic, Emre Akca, Canan Tastimur	Analysis of Barrel Electroplating Line with Process Mining and Petri-Net Model		
8	114	Esha Baidya Kayal, Kabir Chhabra, Devasenathipathy Kandasamy, Raju Sharma, Sameer Bakhshi, Amit Mehndiratta	Automated Texture Feature Based Bone Tumor Segmentation and Image Analysis using Supervised Machine Learning		
9	116	Ankur Chowdhury, Alok K. Saxena, K.D. Joshi	Transient analysis of MGMC Spark gap switches for improved performance in pulse power systems		
10	117	Aman Sah, Jyoti Ranjan Panda, Abhik Gorai, Wriddhi Bhowmik, Anirban Neogi	Highly Selective Triple Band Filter Using Stub Loaded Folded Step Impedance Resonator		



Modelling and Control of a Flexible Link Rotary Servo







Chaity Sarka<mark>r; Kingsuk Majumdar;</mark> Srijan Banerjee; Ranjan kumar Jha; Gyan Prakash

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Chaity Sarkar

Department of Electrical Engineering, Dr. B.C Roy Engineering College, Durgapur



Kingsuk Majumdar

Department of Electrical Engineering, Dr. B.C Roy Engineering College, Durgapur

Srijan Banerjee

Department of Electrical Engineering, Dr. B.C Roy Engineering College, Durgapur

Ranjan kumar Jha

Department of Electrical Engineering, Dr. B.C Roy Engineering College, Durgapur

Gyan Prakash

Department of Electrical Engineering, Dr. B.C Roy Engineering College, Durgapur

Contents

I. Introduction

Control Systems has made giant leaps in the last few decades but the theoretical promises of control systems are not always tested on physical systems. The present work is one attempt to bridge one such gap. This study is madegorinatal@conation. A Flexible Link is also included to the system to enhance the complexity. The objective of the work is to achieve an asymptotically stable system response for flexible link.

Authors	^
Chaity Sarkar Department of Electrical Engineering, Dr. B.C Roy Engineering College, Durgapur	
Kingsuk Majumdar Department of Electrical Engineering, Dr. B.C Roy Engineering College, Durgapur	
Srijan Banerjee Department of Electrical Engineering, Dr. B.C Roy Engineering College, Durgapur	
Ranjan kumar Jha Department of Electrical Engineering, Dr. B.C Roy Engineering College, Durgapur	
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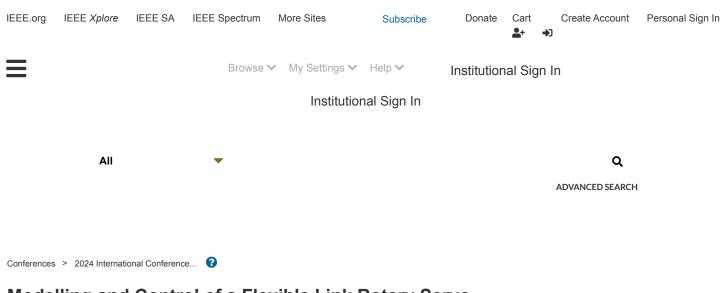
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Chaity Sarkar

Department of Electrical Engineering, Dr. B.C Roy Engineering College, Durgapur

Kingsuk Majumdar

Department of Electrical Engineering, Dr. B.C Roy Engineering College, Durgapur

Srijan Banerjee

Department of Electrical Engineering, Dr. B.C Roy Engineering College, Durgapur

Ranjan kumar Jha

Department of Electrical Engineering, Dr. B.C Roy Engineering College, Durgapur

Gyan Prakash

Department of Electrical Engineering, Dr. B.C Roy Engineering College, Durgapur



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Authors	^
Chaity Sarkar	
Department of Electrical Engineering, Dr. B.C Roy Engineering College, Durgapur	
Kingsuk Majumdar	
Department of Electrical Engineering, Dr. B.C Roy Engineering College, Durgapur	
Srijan Banerjee	
Department of Electrical Engineering, Dr. B.C Roy Engineering College, Durgapur	
Ranjan kumar Jha	
Department of Electrical Engineering, Dr. B.C Roy Engineering College, Durgapur	
Gyan Prakash	
Department of Electrical Engineering, Dr. B.C Roy Engineering College, Durgapur	
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References	~
Keywords	~
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